

# ME 6125 Mechanics of Viscous Fluid

## Lecture 3

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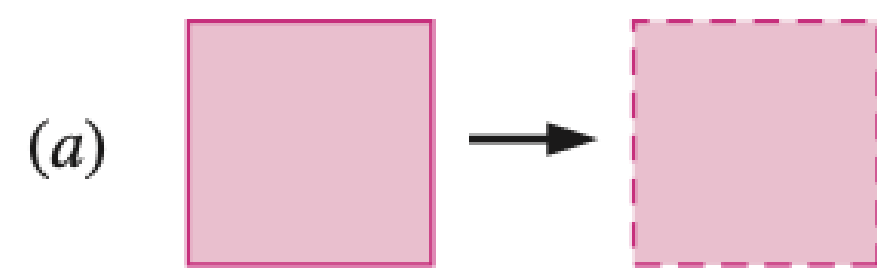
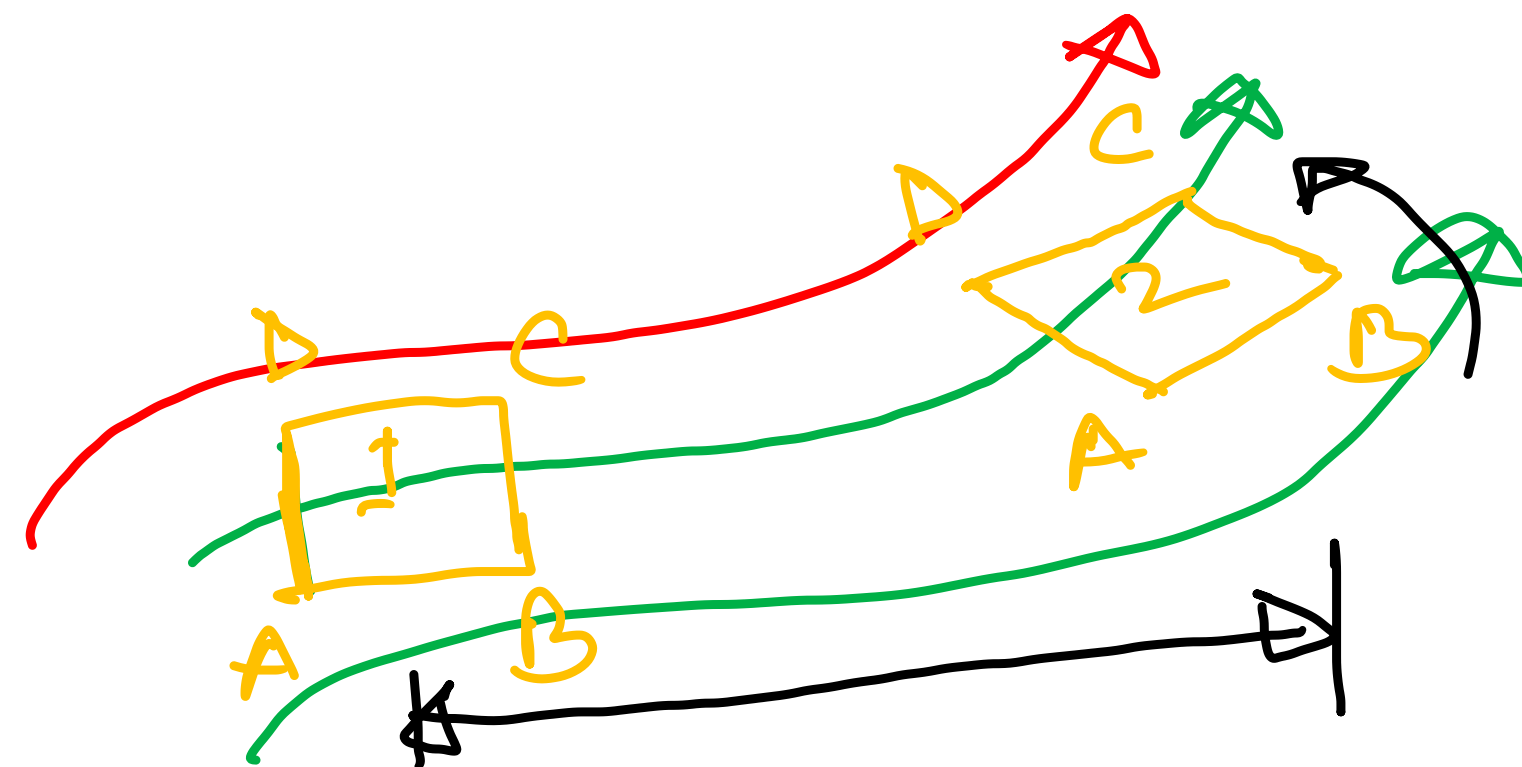


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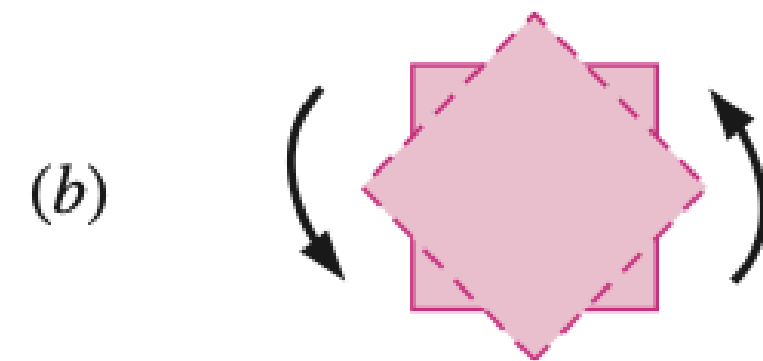
**IMPACT Lab**  
Interfacial Multiscale  
Physics and Transport

- study of motion
- Describing motion of fluids without discussing the forces.



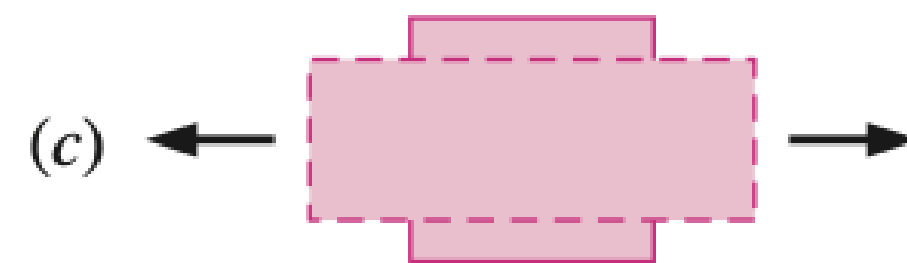
Translation

✓



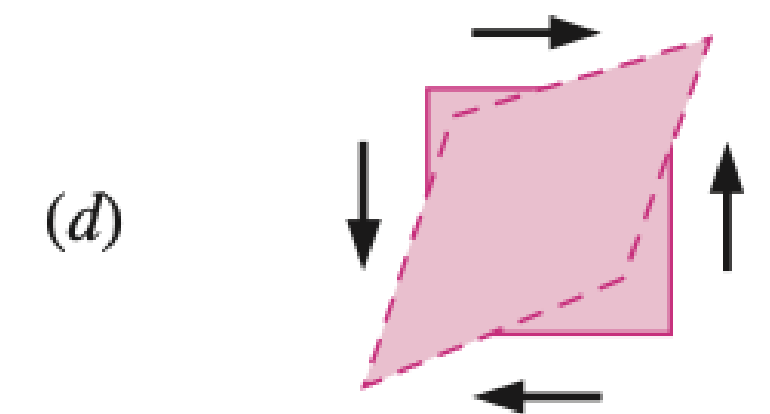
Rotation

✓ solid



Linear strain

solid

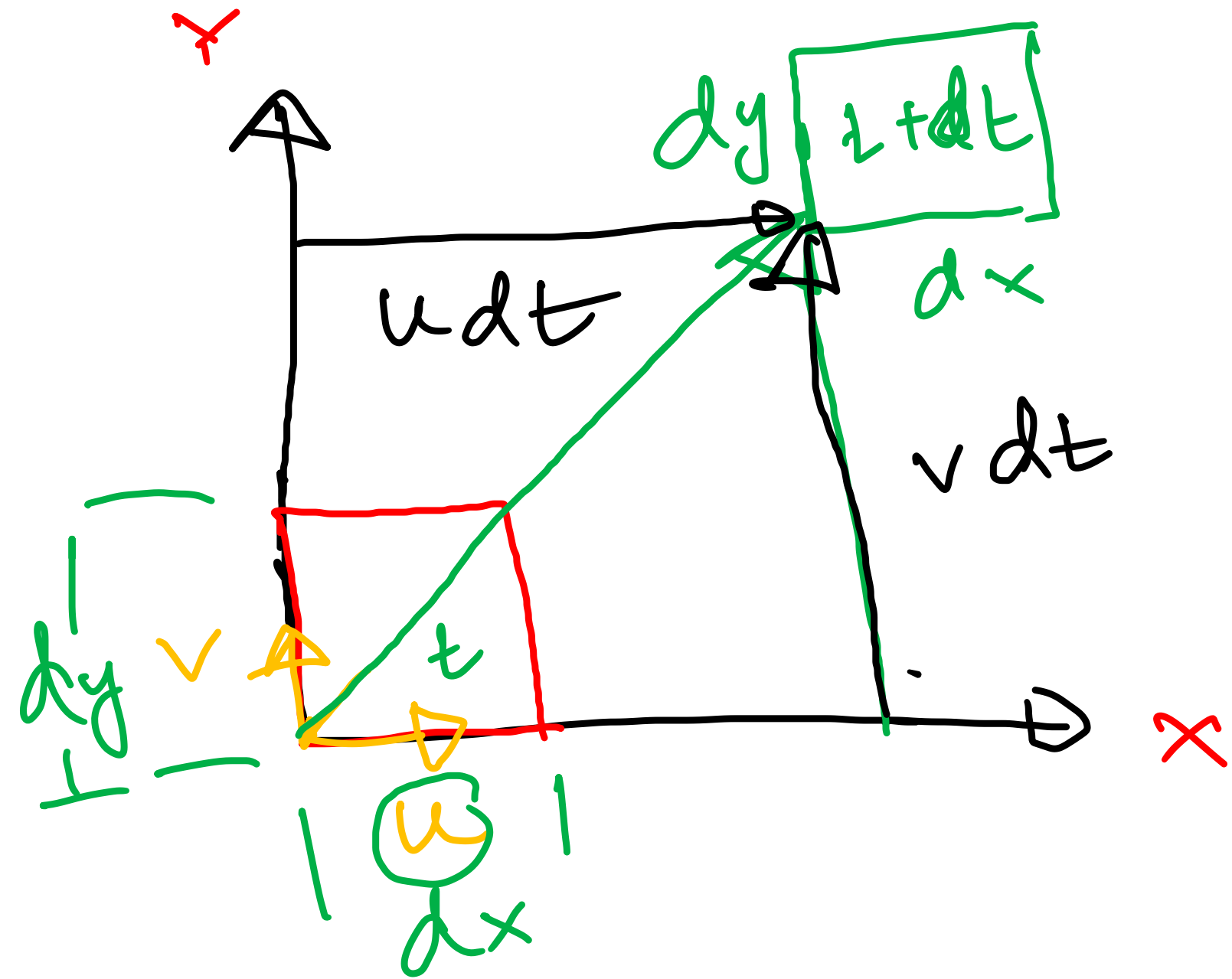


Shear strain

✓



# Translation



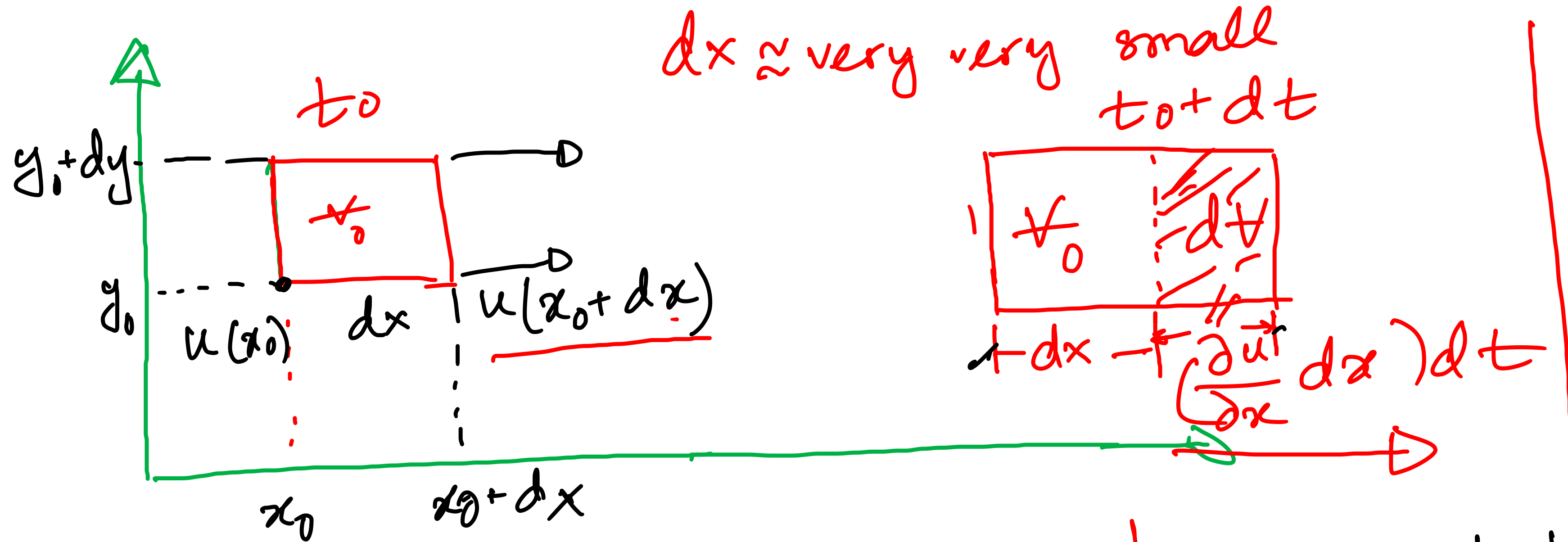
x-velocity =  $u$   
y-velocity =  $v$   
z-velocity =  $w$

Rate of Translation  $\dot{x} = u$

Translation  $x = u dt$   
Rate of translation  $x = \underline{u}$



# Linear Strain Rate



Linear strain  
 $= \frac{\text{new length} - \text{old length}}{\text{old length}}$

Per Taylor series expansion:  
 $u(x_0 + dx) \approx u(x_0) + \frac{\partial u}{\partial x} dx$

\* Linear strain  
 $= \frac{[dx + (\frac{\partial u}{\partial x} dx) dt] - dx}{dx} = \frac{(\frac{\partial u}{\partial x} dx) dt}{dx}$   
 $= \frac{\partial u}{\partial x} dt$

$\epsilon_{xx} = \frac{\partial u}{\partial x}, \epsilon_{yy} = \frac{\partial v}{\partial y}, \epsilon_{zz} = \frac{\partial w}{\partial z}$

Linear strain rate =  $\frac{\partial u}{\partial x}$



# Divergence

$$dV = \left[ \left( \frac{\partial u}{\partial x} dx \right) dt \right] (dy dz) = \frac{\partial u}{\partial x} dt (dx dy dz)$$
$$= \frac{\partial u}{\partial x} dt V_0$$

$$\Rightarrow \frac{\frac{dV}{V_0}}{dt} = \frac{\partial u}{\partial x} = \epsilon_{xx}$$

linear strain rate describes the relative rate of change of volume of the fluid element.

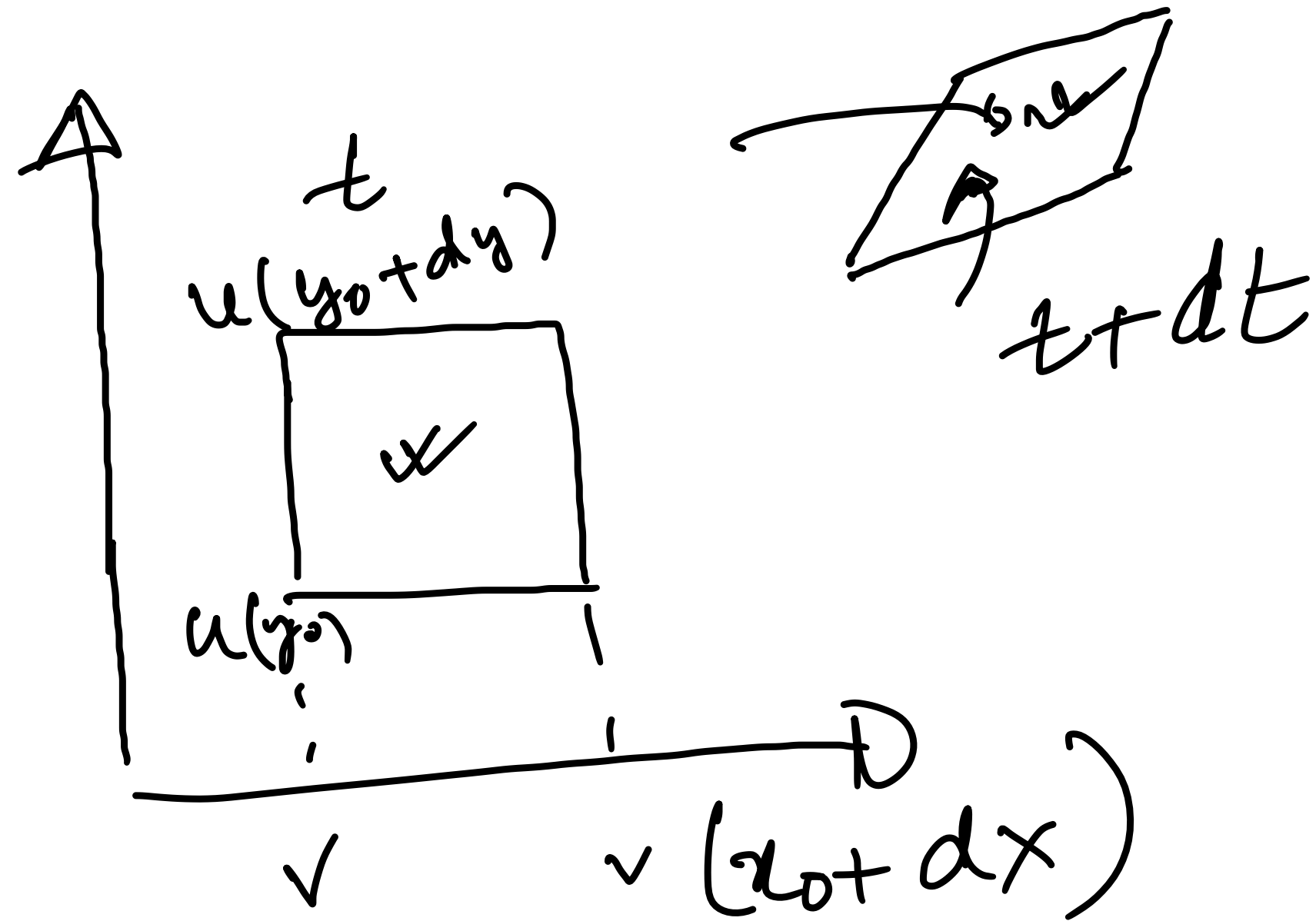
Total rate of change of fluid element volume

$$= \epsilon_{xx} + \epsilon_{yy} + \epsilon_{zz} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \nabla \cdot \vec{v}$$

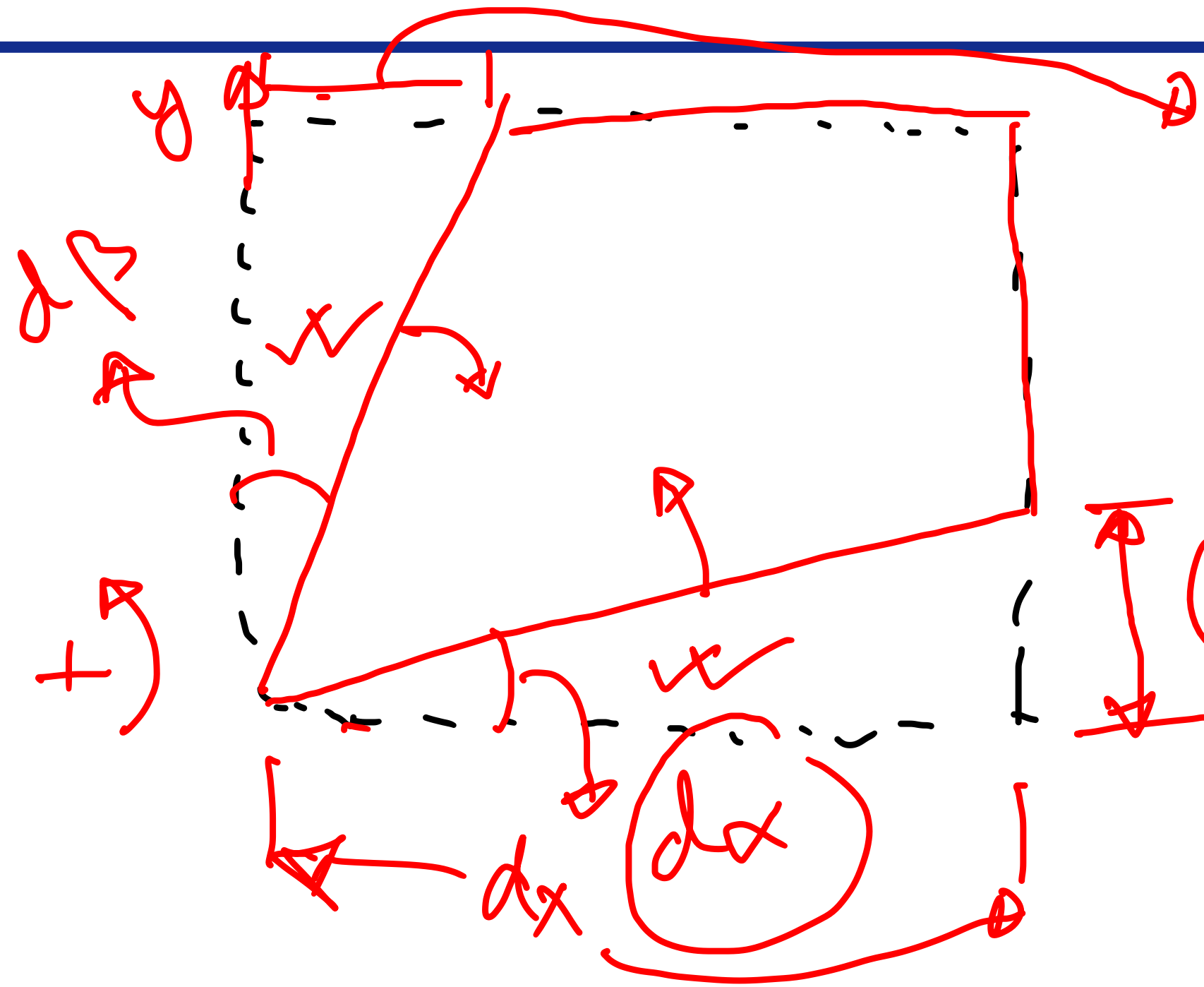
for incompressible fluid,  $\nabla \cdot \vec{v} = 0$  → why?



# Angular strain rate



# Deformation rate



$$dy \left( \frac{du}{dy} dt \right)$$

$$\tan(\alpha) = \frac{\left( \frac{\partial v}{\partial x} dx \right) dt}{dx}$$

$$\left( \frac{\partial v}{\partial x} dx \right) dt$$

$$\Rightarrow \alpha = \left( \frac{\partial v}{\partial x} \right) dt$$

Deformation rate =  $\dot{\gamma}_\alpha = + \frac{\partial v}{\partial x}$

Avg. Angular velocity,  $\Omega_z = \frac{1}{2} (\dot{\gamma}_\alpha + \dot{\gamma}_\beta) = \dot{\gamma}_\beta = - \frac{\partial u}{\partial y}$

$$= \frac{1}{2} \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$



# Shear strain rate



# Rotation and vorticity

